

8-Partitioning Points in 3D, and Efficiently Too

Gianluca Tasinato

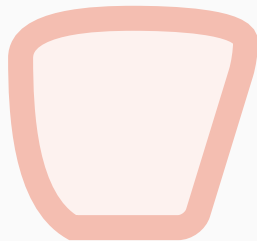
ISTA

Joint work with:

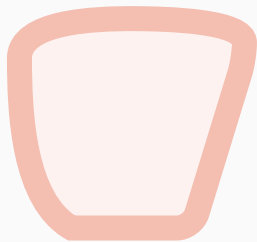
B. Aronov, A. Basit, I. Ramesh, U. Wagner



Prelude: Ham-Sandwich Theorem



Prelude: Ham-Sandwich Theorem



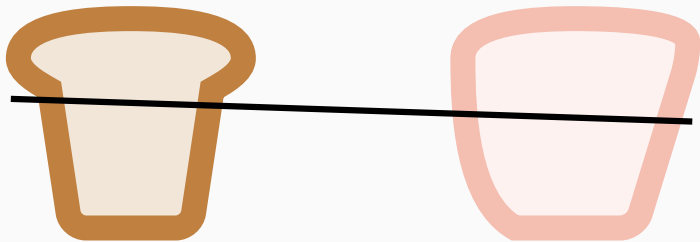
Theorem (Ham-Sandwich Theorem)

Let μ_1, \dots, μ_d nice finite measures¹ on \mathbb{R}^d . Then there is an affine hyperplane $H = \{p \in \mathbb{R}^d \mid \langle x, p \rangle = a\}$ that simultaneously bisects all the measures; i.e., for any $i \leq d$,

$$\mu_i(\{p \in \mathbb{R}^d \mid \langle x, p \rangle > a\}) = \mu_i(\{p \in \mathbb{R}^d \mid \langle x, p \rangle < a\})$$

¹E.g. μ_i uniform probability measure on convex body.

Prelude: Ham-Sandwich Theorem



Theorem (Ham-Sandwich Theorem)

Let μ_1, \dots, μ_d nice finite measures¹ on \mathbb{R}^d . Then there is an affine hyperplane $H = \{p \in \mathbb{R}^d \mid \langle x, p \rangle = a\}$ that simultaneously bisects all the measures; i.e., for any $i \leq d$,

$$\mu_i(\{p \in \mathbb{R}^d \mid \langle x, p \rangle > a\}) = \mu_i(\{p \in \mathbb{R}^d \mid \langle x, p \rangle < a\})$$

¹E.g. μ_i uniform probability measure on convex body.

Grünbaum's Partitioning Problem (Continuous Version)

Problem (Grünbaum; '60)

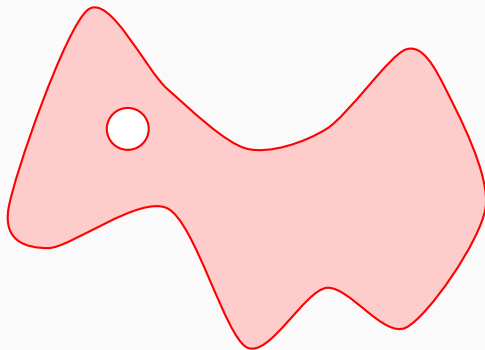
Given a nice probability measure on \mathbb{R}^d , is it possible to find a d -tuple of affine hyperplanes such that the total mass of every open orthant is $\frac{1}{2^d}$?

Grünbaum's Partitioning Problem (Continuous Version)

Problem (Grünbaum; '60)

Given a nice probability measure on \mathbb{R}^d , is it possible to find a d -tuple of affine hyperplanes such that the total mass of every open orthant is $\frac{1}{2^d}$?

$d = 2$: Yes (by Ham-Sandwich theorem)

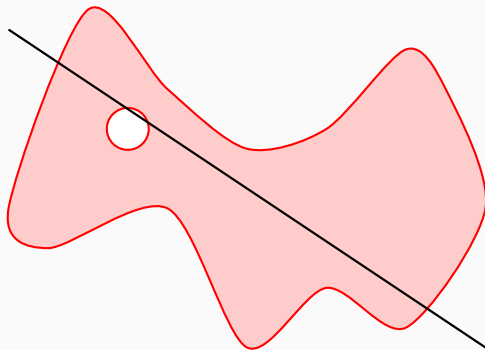


Grünbaum's Partitioning Problem (Continuous Version)

Problem (Grünbaum; '60)

Given a nice probability measure on \mathbb{R}^d , is it possible to find a d -tuple of affine hyperplanes such that the total mass of every open orthant is $\frac{1}{2^d}$?

$d = 2$: Yes (by Ham-Sandwich theorem)

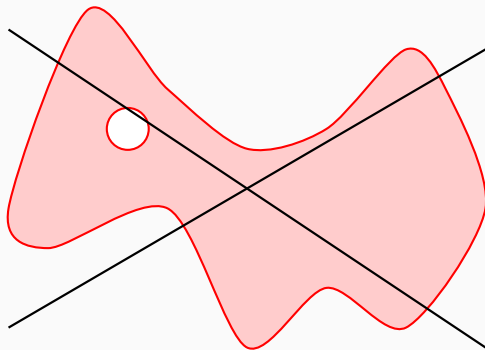


Grünbaum's Partitioning Problem (Continuous Version)

Problem (Grünbaum; '60)

Given a nice probability measure on \mathbb{R}^d , is it possible to find a d -tuple of affine hyperplanes such that the total mass of every open orthant is $\frac{1}{2^d}$?

$d = 2$: Yes (by Ham-Sandwich theorem)



Grünbaum's Partitioning Problem (Continuous Version)

Problem (Grünbaum; '60)

Given a nice probability measure on \mathbb{R}^d , is it possible to find a d -tuple of affine hyperplanes such that the total mass of every open orthant is $\frac{1}{2^d}$?

$d = 3$: Yes, even when asking that:

- ▶ one plane has a prescribed normal direction [Hadwiger; '66].²

²Rediscovered independently by [Yao, Dobkin, Edelsbrunner, Paterson; '89].

Grünbaum's Partitioning Problem (Continuous Version)

Problem (Grünbaum; '60)

Given a nice probability measure on \mathbb{R}^d , is it possible to find a d -tuple of affine hyperplanes such that the total mass of every open orthant is $\frac{1}{2^d}$?

$d = 3$: Yes, even when asking that:

- ▶ one plane has a prescribed normal direction [Hadwiger; '66].²
- ▶ one plane is orthogonal to the other two [Blagojević, Karasev; '16].

²Rediscovered independently by [Yao, Dobkin, Edelsbrunner, Paterson; '89].

Grünbaum's Partitioning Problem (Continuous Version)

Problem (Grünbaum; '60)

Given a nice probability measure on \mathbb{R}^d , is it possible to find a d -tuple of affine hyperplanes such that the total mass of every open orthant is $\frac{1}{2^d}$?

$d = 3$: Yes, even when asking that:

- ▶ one plane has a prescribed normal direction [Hadwiger; '66].²
- ▶ one plane is orthogonal to the other two [Blagojević, Karasev; '16].

Theorem (Aronov, Basit, Ramesh, T., Wagner; '24+)

It is always possible to find a triple of planes where the intersection line of two of them has a prescribed direction.

²Rediscovered independently by [Yao, Dobkin, Edelsbrunner, Paterson; '89].

Grünbaum's Partitioning Problem (Continuous Version)

Problem (Grünbaum; '60)

Given a nice probability measure on \mathbb{R}^d , is it possible to find a d -tuple of affine hyperplanes such that the total mass of every open orthant is $\frac{1}{2^d}$?

Grünbaum's Partitioning Problem (Continuous Version)

Problem (Grünbaum; '60)

Given a nice probability measure on \mathbb{R}^d , is it possible to find a d -tuple of affine hyperplanes such that the total mass of every open orthant is $\frac{1}{2^d}$?

$d = 4$: the problem is still open. It is not known if an equipartition always exists.

Grünbaum's Partitioning Problem (Continuous Version)

Problem (Grünbaum; '60)

Given a nice probability measure on \mathbb{R}^d , is it possible to find a d -tuple of affine hyperplanes such that the total mass of every open orthant is $\frac{1}{2^d}$?

$d \geq 5$: the problem is overconstrained (d^2 degrees of freedom, $2^d - 1$ constraints). Explicit counterexample due to [Avis; '86].

Grünbaum's Partitioning Problem (Discrete Version)

Problem

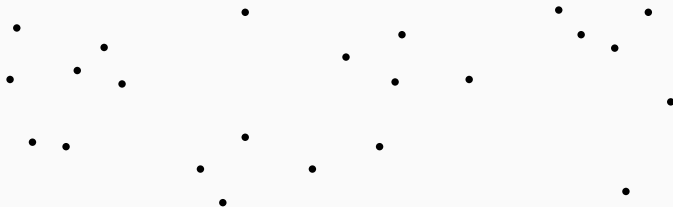
Given a set $P \subseteq \mathbb{R}^d$ of n points in general position, is it always possible to find a d -tuple of affine hyperplanes such that every open orthant contains at most $\lfloor \frac{n}{2^d} \rfloor$ points in P ?

Grünbaum's Partitioning Problem (Discrete Version)

Problem

Given a set $P \subseteq \mathbb{R}^d$ of n points in general position, is it always possible to find a d -tuple of affine hyperplanes such that every open orthant contains at most $\lfloor \frac{n}{2^d} \rfloor$ points in P ?

Ex: $d = 2$

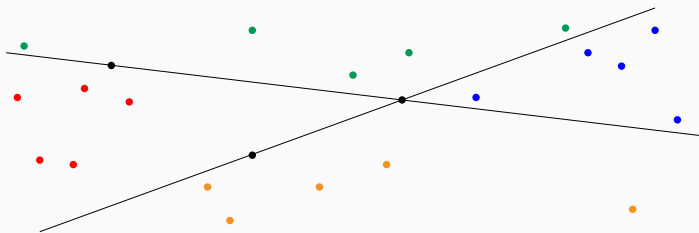


Grünbaum's Partitioning Problem (Discrete Version)

Problem

Given a set $P \subseteq \mathbb{R}^d$ of n points in general position, is it always possible to find a d -tuple of affine hyperplanes such that every open orthant contains at most $\lfloor \frac{n}{2^d} \rfloor$ points in P ?

Ex: $d = 2$

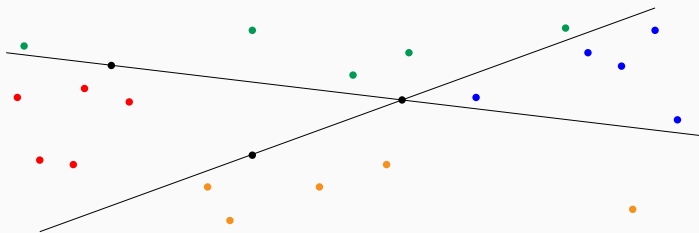


Grünbaum's Partitioning Problem (Discrete Version)

Problem

Given a set $P \subseteq \mathbb{R}^d$ of n points in general position, is it always possible to find a d -tuple of affine hyperplanes such that every open orthant contains at most $\lfloor \frac{n}{2^d} \rfloor$ points in P ?

Ex: $d = 2$



In general, existence of an equipartition for the continuous problem implies existence for discrete version.

Computing 8-partitions

Problem

Let P be a set of n points in general position in \mathbb{R}^3 , compute an 8-partition, i.e. a triple of planes (H_1, H_2, H_3) such that every open orthant contains at most $\lfloor \frac{n}{8} \rfloor$ points in P .

Computational Complexity of the discrete Grünbaum problem

Problem

Let P be a set of n points in general position in \mathbb{R}^3 , compute an 8-partition, i.e. a triple of planes (H_1, H_2, H_3) such that every open orthant contains at most $\lfloor \frac{n}{8} \rfloor$ points in P .

A brute-force algorithm that checks all possible triple of planes finds a solution in $O(n^9)$.

Computational Complexity of the discrete Grünbaum problem

Problem

Let P be a set of n points in general position in \mathbb{R}^3 , compute an 8-partition, i.e. a triple of planes (H_1, H_2, H_3) such that every open orthant contains at most $\lfloor \frac{n}{8} \rfloor$ points in P .

A brute-force algorithm that checks all possible triple of planes finds a solution in $O(n^9)$.

In the '80, an algorithm² that computes in $O(n^6)$ a solution with prescribed normal for one of the planes was obtained.

²[Edelsbrunner; '86] and [Yao, Dobkin, Edelsbrunner, Paterson; '89]

Theorem (Aronov, Basit, Ramesh, T., Wagner; '24+)

Let $P \subseteq \mathbb{R}^3$ a set of n points in general position and $v \in S^2$. Then there is an algorithm that computes an eight-partition (H_1, H_2, H_3) of P with v the normal vector of H_1 in time $O^(nh_2(n)) \leq O^*(n^{\frac{7}{3}})$; where $O^*(\cdot)$ hides polylog factors and $h_2(n) = \max$ number of halving lines of a planar set of n points.*

Theorem (Aronov, Basit, Ramesh, T., Wagner; '24+)

Let $P \subseteq \mathbb{R}^3$ a set of n points in general position and $v \in S^2$. Then there is an algorithm that computes an eight-partition (H_1, H_2, H_3) of P with v the normal vector of H_1 in time $O^(nh_2(n)) \leq O^*(n^{\frac{7}{3}})$; where $O^*(\cdot)$ hides polylog factors and $h_2(n) = \max$ number of halving lines of a planar set of n points.*

Note: the asymptotic behaviour of $h_2(n)$ is not known. Best bounds are:

- $O(n^{\frac{4}{3}})$ [Dey; '97];
- $\Omega(ne^{\sqrt{\log n}})$ [Tóth; '01]

The Algorithm

Preliminaries

Properties of the Point Set

💡: We start by finding a plane that bisects P and it has v as its normal. This divides P in two sets R (points above) and B (points below); we can search for a solution among pairs of planes that simultaneously bisect both R and B .

Properties of the Point Set

💡: We start by finding a plane that bisects P and it has v as its normal. This divides P in two sets R (points above) and B (points below); we can search for a solution among pairs of planes that simultaneously bisect both R and B .

Without loss of generality, the first plane is horizontal; up to adding “dummy” points, we can also assume $n = 8k + 7$.

Properties of the Point Set

💡: We start by finding a plane that bisects P and it has v as its normal. This divides P in two sets R (points above) and B (points below); we can search for a solution among pairs of planes that simultaneously bisect both R and B .

Without loss of generality, the first plane is horizontal; up to adding “dummy” points, we can also assume $n = 8k + 7$.

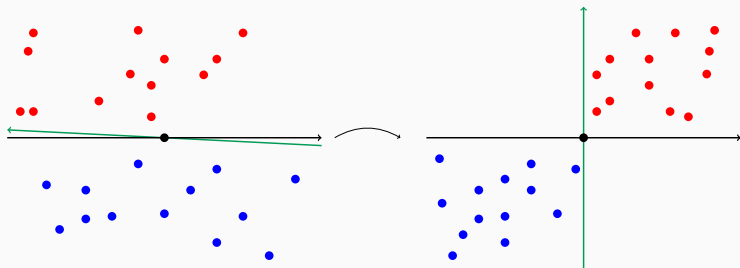
By applying a suitable generic linear transformation we can assume that $R \subseteq \{x > 0, z > 0\}$ and $B \subseteq \{x < 0, z < 0\}$.

Properties of the Point Set

💡: We start by finding a plane that bisects P and it has v as its normal. This divides P in two sets R (points above) and B (points below); we can search for a solution among pairs of planes that simultaneously bisect both R and B .

Without loss of generality, the first plane is horizontal; up to adding “dummy” points, we can also assume $n = 8k + 7$.

By applying a suitable generic linear transformation we can assume that $R \subseteq \{x > 0, z > 0\}$ and $B \subseteq \{x < 0, z < 0\}$.



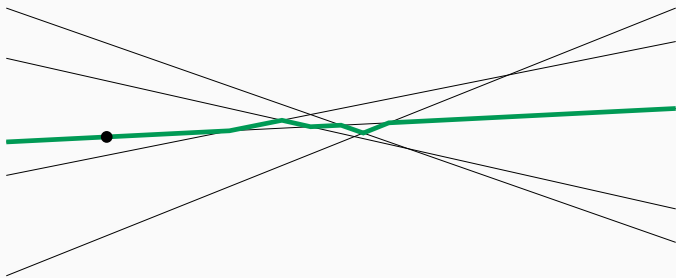
Duality

By dualizing, R and B are transformed to an arrangement of planes $\mathcal{A}(R)$ and $\mathcal{A}(B)$.

Duality

By dualizing, R and B are transformed to an arrangement of planes $\mathcal{A}(R)$ and $\mathcal{A}(B)$.

A (primal) plane bisects R (resp. B) iff the corresponding dual point has half of the planes in $\mathcal{A}(R)$ (resp. $\mathcal{A}(B)$) above and half below, i.e. it lies on the median level.



The Intersection Curve

Any plane in a solution has to simultaneously bisect both R and B , hence its dual point has to belong to L , the intersection of the median levels of $\mathcal{A}(R)$ and $\mathcal{A}(B)$.

The Intersection Curve

Any plane in a solution has to simultaneously bisect both R and B , hence its dual point has to belong to L , the intersection of the median levels of $\mathcal{A}(R)$ and $\mathcal{A}(B)$.

Lemma

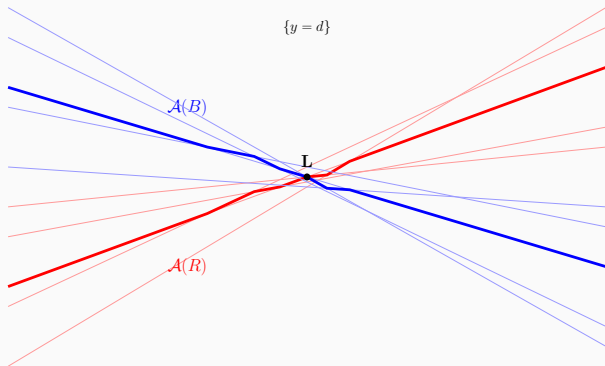
Under the hypothesis on R and B , L is a connected y -monotone curve.

The Intersection Curve

Lemma

Under the hypothesis on R and B , L is a connected y -monotone curve.

Proof [💡]:



Lemma

The intersection curve L can be computed in time $O^(n + m)$ where m is the complexity of the curve.*

Lemma

The intersection curve L can be computed in time $O^(n + m)$ where m is the complexity of the curve.*

What is the worst case scenario for m ?

Lemma

The intersection curve L can be computed in time $O^(n + m)$ where m is the complexity of the curve.*

What is the worst case scenario for m ?

- ▶ If R and B are just in general position, m is $\Theta(h_3(n))$, where $h_3(n)$ is the maximum number of halving planes in a set of n points in \mathbb{R}^3 . Best known bound is $O(n^{\frac{5}{2}})$ [Sharir, Smorodinsky, Tardos; '01].

Lemma

The intersection curve L can be computed in time $O^(n + m)$ where m is the complexity of the curve.*

What is the worst case scenario for m ?

- ▶ If R and B are just in general position, m is $\Theta(h_3(n))$, where $h_3(n)$ is the maximum number of halving planes in a set of n points in \mathbb{R}^3 . Best known bound is $O(n^{\frac{5}{2}})$ [Sharir, Smorodinsky, Tardos; '01].
- ▶ Under our separation assumptions on R and B , m is $\Theta(\underbrace{n h_2(n)}_{O(n^{4/3})}) = O(n^{7/3})$.

The Algorithm

Geometric Idea

Alternating Sums

Goal: Find a pair of points in L whose dual planes simultaneously four-partition R and B in the primal.

Alternating Sums

Goal: Find a pair of points in L whose dual planes simultaneously four-partition R and B in the primal.

For a (dual) point $p \in \mathbb{R}^3$, denote by R_p^+ the set of red planes strictly above p (R_p^- , B_p^\pm defined in similar fashion).

Alternating Sums

Goal: Find a pair of points in L whose dual planes simultaneously four-partition R and B in the primal.

For a (dual) point $p \in \mathbb{R}^3$, denote by R_p^+ the set of red planes strictly above p (R_p^-, B_p^\pm defined in similar fashion).

For a pair of points $p, q \in L$, their red/blue alternating sum is

$$\begin{aligned} X(p, q) &= |R_p^+ \cap R_q^+| - |R_p^- \cap R_q^+| - |R_p^+ \cap R_q^-| + |R_p^- \cap R_q^-| \\ Y(p, q) &= |B_p^+ \cap B_q^+| - |B_p^- \cap B_q^+| - |B_p^+ \cap B_q^-| + |B_p^- \cap B_q^-| \end{aligned}$$

Alternating Sums

Goal: Find a pair of points in L whose dual planes simultaneously four-partition R and B in the primal.

For a (dual) point $p \in \mathbb{R}^3$, denote by R_p^+ the set of red planes strictly above p (R_p^-, B_p^\pm defined in similar fashion).

For a pair of points $p, q \in L$, their red/blue alternating sum is

$$X(p, q) = |R_p^+ \cap R_q^+| - |R_p^- \cap R_q^+| - |R_p^+ \cap R_q^-| + |R_p^- \cap R_q^-|$$

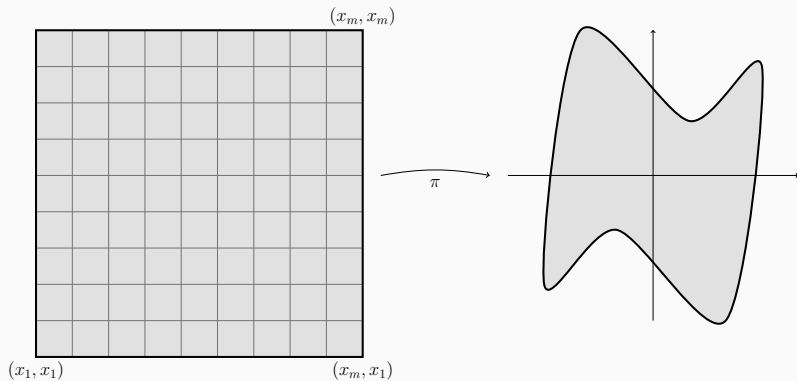
$$Y(p, q) = |B_p^+ \cap B_q^+| - |B_p^- \cap B_q^+| - |B_p^+ \cap B_q^-| + |B_p^- \cap B_q^-|$$

Lemma

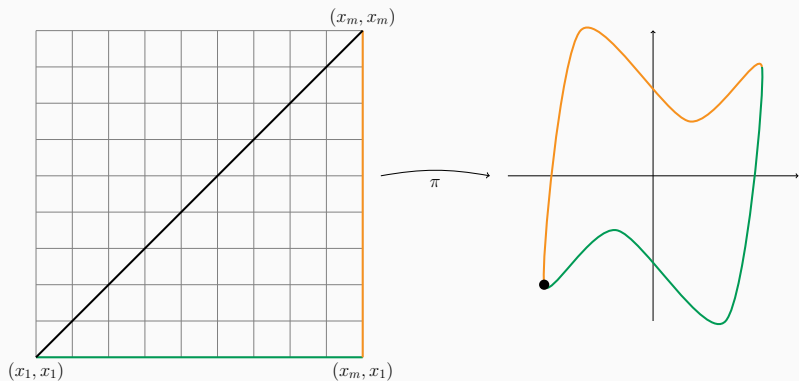
Two planes h_1, h_2 simultaneously 4-partition R and B if and only if their duals h_1^, h_2^* lie on L and $X(h_1^*, h_2^*) = Y(h_1^*, h_2^*) = 0$.*

The Geometric Idea

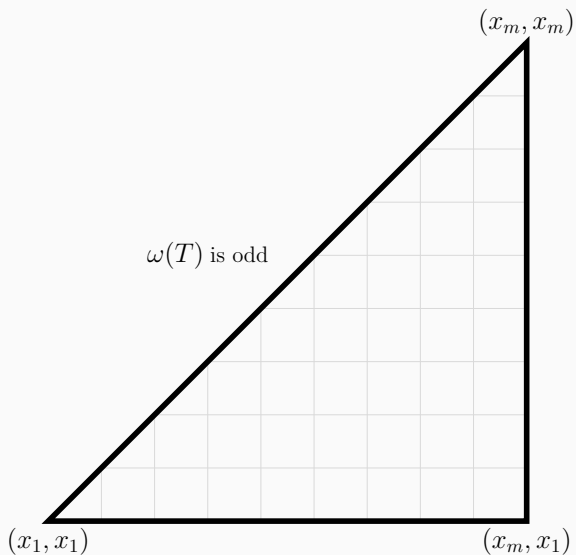
Using the alternating sums, we can define a map $\pi : L^2 \rightarrow \mathbb{R}^2$,
 $(p, q) \mapsto (X(p, q), Y(p, q))$.



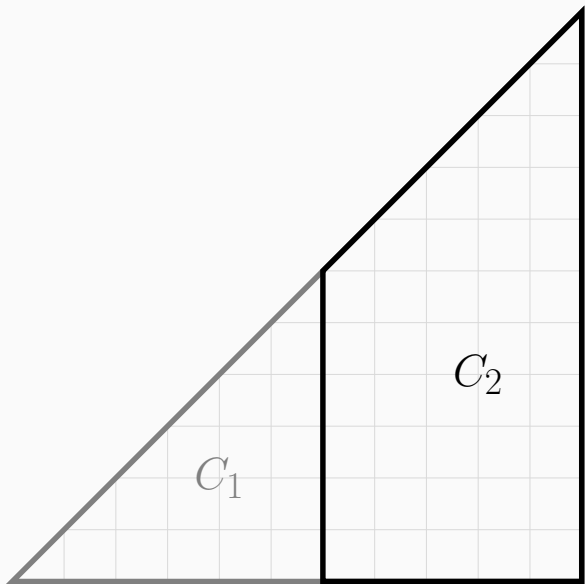
The Geometric Idea



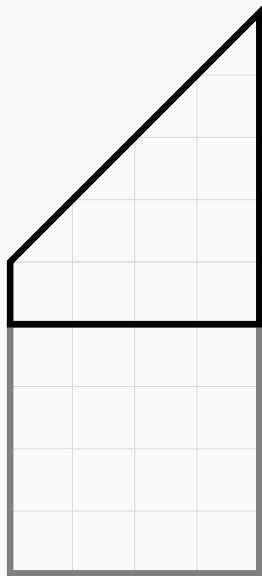
The Geometric Idea



The Geometric Idea



The Geometric Idea



Complexity of the Algorithm

Step 0: Compute L

$$O^*(n + m)$$

Complexity of the Algorithm

Step 0: Compute L $O^*(n + m)$

Step 1: Fix $C = T$ and compute $\pi(C)$; if it meets 0 we stop. $O(n + m)$

Complexity of the Algorithm

Step 0: Compute L $O^*(n + m)$

Step 1: Fix $C = T$ and compute $\pi(C)$; if it meets 0 we stop. $O(n + m)$

Step 2: Construct two simple curves C_1, C_2 by cutting C vertically or horizontally. $O(|C|)$

Complexity of the Algorithm

- Step 0:* Compute L $O^*(n + m)$
- Step 1:* Fix $C = T$ and compute $\pi(C)$; if it meets 0 we stop. $O(n + m)$
- Step 2:* Construct two simple curves C_1, C_2 by cutting C vertically or horizontally. $O(|C|)$
- Step 3:* Compute $\pi(C_1)$ and $\pi(C_2)$; if either C_1 or C_2 meets 0 we have found a solution and stop. $O(n + |C_1| + |C_2|)$

Complexity of the Algorithm

- Step 0:* Compute L $O^*(n + m)$
- Step 1:* Fix $C = T$ and compute $\pi(C)$; if it meets 0 we stop. $O(n + m)$
- Step 2:* Construct two simple curves C_1, C_2 by cutting C vertically or horizontally. $O(|C|)$
- Step 3:* Compute $\pi(C_1)$ and $\pi(C_2)$; if either C_1 or C_2 meets 0 we have found a solution and stop. $O(n + |C_1| + |C_2|)$
- Step 4:* Compute $\omega(C_1)$ and $\omega(C_2)$. Replace C with the one with odd winding number and go to *Step 2*. $O(n + |C_1| + |C_2|)$

Complexity of the Algorithm

Step 0: Compute L $O^*(n + m)$

Step 1: Fix $C = T$ and compute $\pi(C)$; if it meets 0 we stop. $O(n + m)$

Step 2: Construct two simple curves C_1, C_2 by cutting C vertically or horizontally. $O(|C|)$

Step 3: Compute $\pi(C_1)$ and $\pi(C_2)$; if either C_1 or C_2 meets 0 we have found a solution and stop. $O(n + |C_1| + |C_2|)$

Step 4: Compute $\omega(C_1)$ and $\omega(C_2)$. Replace C with the one with odd winding number and go to *Step 2*. $O(n + |C_1| + |C_2|)$

Total cost: $|C|$ is always $O(m)$ and we loop at most $O(\log m)$ times $\Rightarrow O^*(n + m)$.

Complexity of the Algorithm

Step 0: Compute L $O^*(n + m)$

Step 1: Fix $C = T$ and compute $\pi(C)$; if it meets 0 we stop. $O(n + m)$

Step 2: Construct two simple curves C_1, C_2 by cutting C vertically or horizontally. $O(|C|)$

Step 3: Compute $\pi(C_1)$ and $\pi(C_2)$; if either C_1 or C_2 meets 0 we have found a solution and stop. $O(n + |C_1| + |C_2|)$

Step 4: Compute $\omega(C_1)$ and $\omega(C_2)$. Replace C with the one with odd winding number and go to *Step 2*. $O(n + |C_1| + |C_2|)$

Total cost: $|C|$ is always $O(m)$ and we loop at most $O(\log m)$ times $\Rightarrow O^*(n + m)$.

Since m is $\Theta(nh_2(n))$ and $h_2(n)$ is $O(n^{\frac{4}{3}})$ we have the desired $O^*(n^{\frac{7}{3}})$ running time.

Hard questions:

- Is it always possible to equipartition a nice measure/point set in \mathbb{R}^4 ?
- Better characterize the asymptotic behaviour of $h_2(n)$ and $h_3(n)$.

Hard questions:

- Is it always possible to equipartition a nice measure/point set in \mathbb{R}^4 ?
- Better characterize the asymptotic behaviour of $h_2(n)$ and $h_3(n)$.

(Potentially) easier questions:

- Is it possible to compute a solution in $o(nh_2(n))$?
- Find an algorithm for the other “types” of equipartitions (e.g. orthogonality condition or prescribed intersection).

Thank You!